

Bill Culley, President John Amend, CTO

April 26, 2012





## Problems with Robotic Gripping





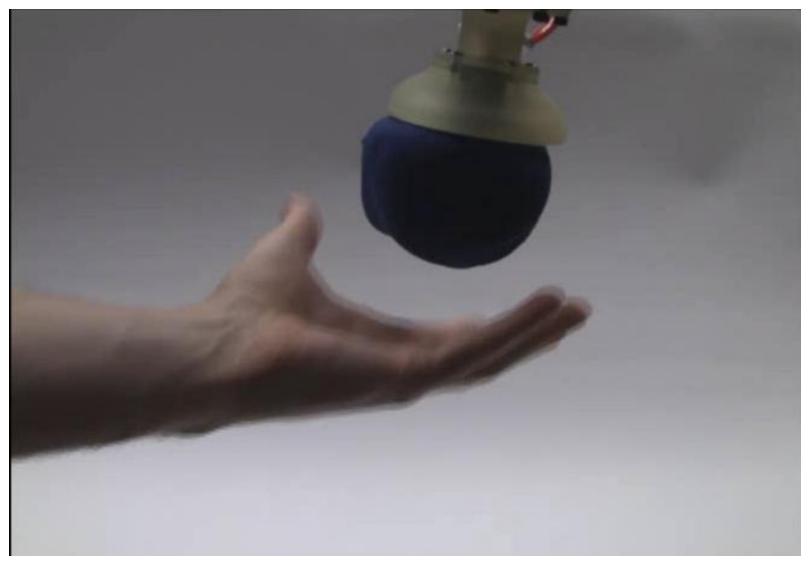






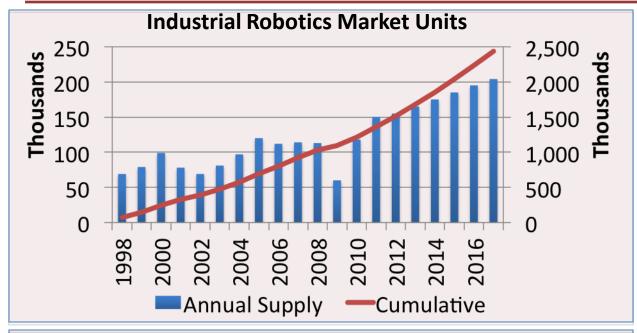
## Jamming Gripper

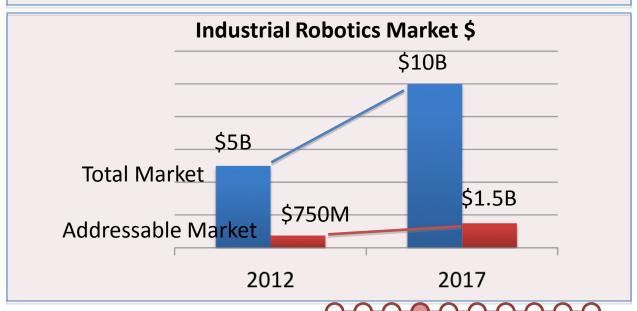




### **Market Potential**







# 2% of existing market = \$15 - \$30M in sales

- Industrial market only
- Existing market only

## **Enabling lower-level industrial processes**

- >1B manuf. Laborers
- ~\$10B labor costs
- 5% of tasks addressable
- \$500M niche market

#### **Surgical Robotics**

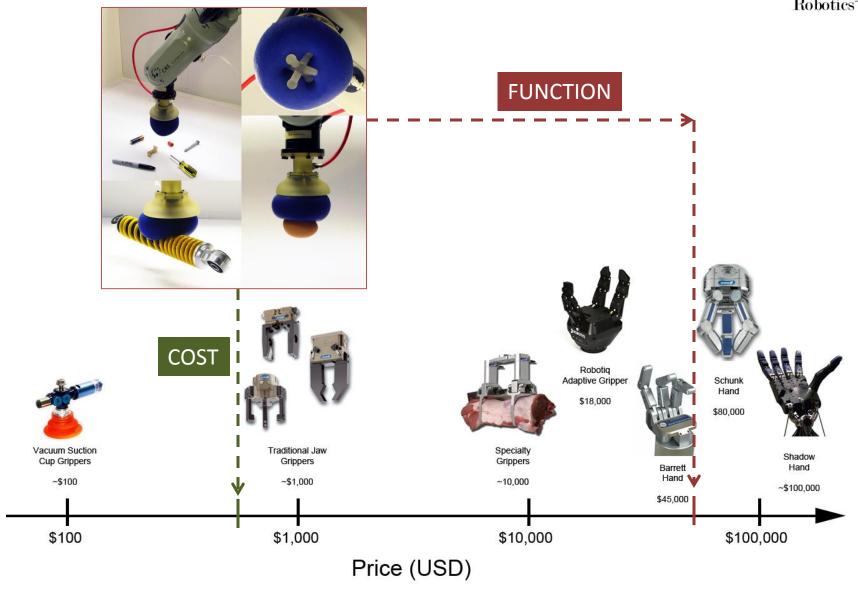
- \$1B market today
- \$5B by 2014

#### **Military Robotics**

• \$10B by 2016

## Competitive Advantage





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## Target Market

















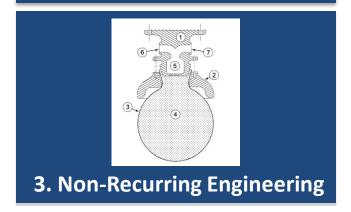


### Revenue Model









Price \$499 - \$2,499 Cost \$100 - \$1,000

Price

\$49 - \$499 Cost \$5 - \$200



Price \$25,000 - \$100,000 Per contract

3.







### Company Structure & Growth



### **Company Structure**

#### **Product Development**

- Relies on core technology
- Involve strategic partners
- Expand through adjacencies

#### **Manufacturing**

- Plastic extrusion outsourced
- Hardware purchased
- Granular material contracted

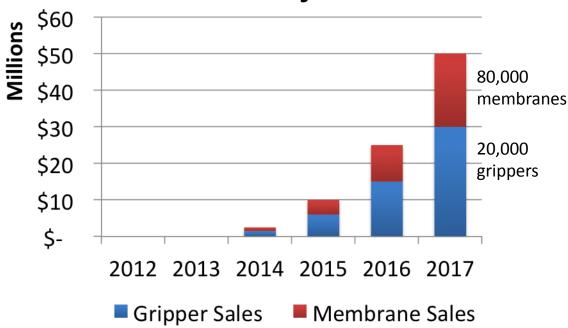
#### Sales & Marketing

- Robotics trade shows
- Detail sales to partners
- Direct design for end-users

#### **Distribution**

- OEM for robotics solutions
- Direct replacement sales
- Direct engineering contracts

### **Sales Projections**



### **Future Expansion**







**Prosthetics** 



**Home Robotics** 



## SofGrip Team



Bill Culley, President is a 2012 MBA candidate at the Johnson School at Cornell University, with experience raising \$150k for his previous startup and successfully exiting. Bill was a management consultant with Oliver Wyman, and holds BS and MEng degrees from Cornell in mechanical engineering.



<u>John Amend, CTO</u> is a PhD candidate in mechanical engineering with the Creative Machines Lab at Cornell University. John has published in several top robotics journals, and has previously performed robotics design research in mechanical engineering at SUNY Buffalo. John is the recipient of the National Science Foundation Graduate Research Fellowship.

#### **Technical Advisory Board**



<u>Hod Lipson, PhD '98</u> - Associate Professor of Mechanical Engineering, Cornell University, Ithaca, NY



<u>Eric Brown, PhD '07</u>- Assistant Professor in Natural Sciences, University of California, Merced, CA



<u>Heinrich M. Jaeger, PhD '87</u> - Professor of Physics, University of Chicago, Chicago, IL



### **Investment & Exit**



#### **Non-dilutive Financing**

- Sub-licensing IP for non-core fields of use
- Exclusive options on developed product applications
- Non-recurring engineering contracts
- NSF grant funding
- Business plan competition prize money

#### **Equity Financing**

- \$1-2M Convertible Notes
  - employ an applied physicist and a product developer, design products for strategic partners
- \$2-5M Series A
  - Product line development and business development
- \$5-10M Series B
  - Move multiple product lines into production and ramp up sales

#### **Exit**

Strategic acquisition by a major robotics company

#### **Potential acquirers**

- Toshiba Machine Co.
- Fanuc Robotics
- Nissan Motors
- Adept Technology
- Stäubli-Unimation
- ABB Group
- KUKA Robotics
- iRobot
- Willow Garage

Thank You Q&A

